



Installation and Operation Manual





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6.5



1. Download and insta

The **AXMART**[®] is compatible with GS6, GPS, GFS, GP7, GP8 and GBH actuators versions. This software is free and available on Google Play for Android version (v5.0 or higher) and on Apple store for the Apple version.

Software name : AXMART (v3)

1.1 Android version

Installation :



Access requested by AXMART :

- Access to position
- Access to gallery/photos

The device GPS must be activated

1.2 Apple version

Installation :



- Before launching **AXMART**, the device clock must be correct.
 - During the switch between winter and summer time, a connection to the actuators is imperative for clocks synchronisation.



2. General description

Because of the screen size, the display isn't the same according the device (tablet or smartphone). Les functionalities are the same.

2.1 Smartphone display

Connection to an actuator					
ER10 GS6 -1 88:6b:0f:8f:89:fd					
VT2400 GS6 -2 88:6b:0f:8d:45:bc					
MT50 GS6 -3 88:6b:0f:4a:58:ab					
VS150 GPS -4 88:6b:0f:7f:12:fc					
Start actuator scanning					

Operating and control mode selection

÷									
\$	Sta	atus	Pro	<					
Open	Z Inter	Close	STOP	Prog.	Ø Posi				
Positio	n	38 %			+				
				Manual	control				
		Parar	neters						
Name			VS150	GPS -4					
Current	mode		Prog.						
Id	ld 88:6b:0f:7f:12:fc								
Positior	ı		Open						
Automatic refresh									
Refresh status C									



Weekly scheduling



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2.2 Tablet display

Connection to an actuator

≡	AXMART®
ER10 GS6 -1 88:6b:0f:8f:89:fd	
VT2400 GS6 -2 88:6b:0f:8d:45:bc	
MT50 GS6 -3 88:6b:0f:4a:58:ab	
VS150 GPS -4 88:6b:0f:7f:12:fc	
Start	actuator scanning

Operating and control mode selection			trol mode	Weekly s	scheduling
÷				AXMART [®]	
Open	570P	Close	/금 Wired	Parameters Open	+ 00:00
	Parameters			Mon - Tue	14h04
Name Current mode	Name ER10 GS6-1 Current mode Prog.				
ld		88:6b	:0f:e8:55:a5		
Position		Open			
Temperature		32°C			
Min tempera	Min temperature 0°C				
Max tempera	ature	48°C			
Automatic refresh					
Refresh status C			C		

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3. Connection to an actuator







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4. Stat

The status screen shows all actuator parameters in real time.

← ∧×	MART®	
Status	Prog. 🗲 🗲	Sharing actuator status (see chapter 5.5)
Enter cot	rolling mode	
Para	meters	
Name	ER GS6 -1	Actuator name
Current mode	Bluetooth control	Current selected control mode (Bluetooth®, prog, posi and wired)
ld	88:6b:0f:f8:6c:6d	Actuator MAC address
Position	Open	Current position (open, closed, intermediate)
Position	0%	Current position (percentage of opening)
Température	38°C	Current temperature inside actuator enclosure
Min temperature	22°C	Minimum temperature
Max temperature	38°C	Maximum temperature
Nb. of cycles	16	Number of operating periods before and after a rest period (since the first start of the actuator)
Operating time	00h 01m 48s	Total functioning time
Nb. of faults	0	Number of errors (temperature, overtorque)
Nb. of EEPROM faults	s 0	Internal number of errors (microcuts during writing memory).
Cryptogram	12FECC859CC689A3	Password encryption. Needed for password recovery process.
Batterie charge	Charged	Battery charge status
BBPR status	Available	BBPR availability (battery connected, safety temperature not reached and charge level > 70 %)
NB. of power failure	0	Number of power cuts and starts of BBPR unit
Overtorque nb.	0	Number of overtorques
Overtemp nb.	0	Number of excessive temperature
Safety position	Closed	Backup position, reached in case of power failure
Setpoint signal	4-20mA - Normal	Type of setpoint analogic signal (4-20 mA or 0-10 V)
Feedback signal	4-20mA - Normal	Type of feedback analogic signal (4-20 mA or 0-10 V)
Autor	matic refresh	
Refresh	status C	

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5. Functionalities

5.1 Control activation

The functionalities described from this section allow the actuator control. Therefore, the actuator password is required (default password: pwd or User for actuators .GBH).







Bluetooth Control

Actuator status Parameters

5.2 Functioning modes

Mode « Bluetooth® control » :

This mode is activated using these functions:



This mode allows a local control (on-off) of the actuator.

Mode « Positioning » :

This mode is activated using these functions:

		Position			Actuator status			
Posi	or	-	38 %	+ Manual control		F Current mode	Parameters POSI	
					L			

This mode allows a local control of the actuator with percentage of opening.

This mode also gives priority to electric wiring on terminals 15/16 (setpoint) and 13/14 (feedback)

Mode « Wired control » :

This mode is activated using this function:

Current mode

Wired

宕

This mode gives priority to electric wiring on power supply terminals (1, 2, 3 and 4).

Mode « Weekly scheduling » :

This mode is activated using this function:



This mode gives priority to stored tasks of the scheduler.

Actuator status					
Parameters					
Current mode	Prog.				



Each functioning mode activation deactivates the other ones. Before exiting AXMART, It's mandatory selecting the mode corresponding to the desired use of the actuator.



5.3 Local control

AXMART allows to locally manipulate the actuator.

Basic control :



Drives the actuator until open position (90°) or final position (180°) in case of 3-position-actuator.

Drives the actuator until intermediate position (in case of 3-position-actuator).



Drives the actuator until closed position (0°)



Actuator stops

Control with percentage of opening (positioning) :

Position	38 %	+
		Manual control

Using « Manual control » drives the actuator to the selected percentage of opening.



Each functioning mode activation deactivates the other ones. Before exiting AXMART, It's mandatory selecting the mode corresponding to the desired use of the actuator.



5.4 Weekly scheduling

With AXMART, it's possible to automate and making standalone the actuators, using a weekly scheduler (capacity of 20 tasks).







Task scheduling:

Task (slot n.0 on ER GS6	-1)	
Start time	16:10	Task starting time
Position	Open	Position the actuator has to reach or position inversion
Duration	<u>10</u> : <u>0</u>	Optional: Duration hold-position time () (This duration includes the actuator operating time)
Final position	Close	Optional: position to reach after the previous duration
Mon Tue Wed Thu Fri	Sat Sun	Days for task start
Delete 🔟		
Save		
Cancel		

Example of two operations with an hold position time:







5.5 Sharing and sending status report

The icon sending a complete report including all actuator parameters and using the communication functions available on the device (Bluetooth®, Wifi direct, cloud, Email...)

Report content (available in English only):

Actuator VS300 GS6 -1 (88:6b:0f:8f:89:fd)

Generated on : dd/mm/yyyy - hh:mm:ss

State

Property	Value						
Name	VS150 GPS	VS150 GPS -4					
Address	88:6b:0f:8f	38:6b:0f:8f:89:fd (NB when generated on iOS, MAC addresses ends by XX:XX:XX)					
Status mode	OK						
Temperature	45°C						
Temperature Min	-9°C						
Temperature Max	64°C						
Cycle counter	2504	504					
Working time	06h 36m 21	S					
Fault counter	245						
EEPROM error counter	0						
Current mode	Prog.						
Password	12FEC69B94	1					
Charging level	Charged						
Battery status	Available						
Nb power fail	242						
Nb torque fault	220						
Nb temperature fault	25						
Actuator position	0%						
Start ramp	0						
Torque limit	80						
Torque delay	1						
Gear unlock	0						
Temp regulation	10						
Temp security	70						
BBPR position	Closed						
Pilotage wired	0						
SetPoint sensor point	4-20mA						
SetPoint sensor direction	Rising						
Feedback sensor point	4-20mA						
Feedback sensor direction	Rising						
Туре	GS6						
Rotation direction	Normal						
	SlotId	Duration	Time	Com	mand	Posi	tion
Tasks	0	10:00	16h10	Ou ⁻	vrir	Ferm	eture
	TRUE	TRUE	FALSE	FALSE	TRUE	Sat	TRUE
User picture							



6. Actuator setup



6.1 Modification of the actuator name

Type in the field « **Name** » the new name of the actuator (12 characters maximum).



÷	AXMART [®]	
Settings		
Name	VS150 GPS -4	

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Password

6.2 Modification of the actuator password

for obvious safety reasons , the password must be modified at the first use of the actuator. Type the new password in the field « **Password**».

The icon () shows the characters.



8 characters maximum Available characters: a-z, A-Z, 0-9 only



6.3 Wiring setup

Concerns the control with the actuator electric wiring.

- 4-wires : specific wiring with all terminals of the power supply terminal block or for pulse control wiring.
- Standard : for all other wiring including positioning.







6.4 Positioning setup

The setpoint signal (terminals 15/16) is the actuator positioning signal. The feedback signal gives the actuator position (terminals 13/14).

- 0-10 V : Setpoint or feedback with voltage range 0 V = 0° ; 10 V = 90°
- 4-20 mA : Setpoint or feedback with intensity range
 4 mA = 0°; 20 mA = 90°
- Normal : Correspondence signal/position as descripted above
- Inverted : Inverted voltage/intensity ranges

 $10~V=0^\circ$; $0~V=90^\circ$ and $20~mA=0^\circ$; $4~mA=90^\circ$



Enter

Positioning Setpoint signal	
0-10mV	4-20mA
Normal	Inverted
Feedback signal	
0-10mV	4-20mA
Normal	Inverted

6.5 FAILSAFE safety position setup

The FAILSAFE system insure that the actuator will reach a predetermined safety position in case of power failure.

- Open : The valve reaches open position in case of power failure.
- Closed : The valve reaches closed position in case of power failure (default).
- Inactive: The FAILSAFE unit is disabled (example : maintenance...)



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CR-TEC Engineering Inc. 15 Orchard Park Road, Unit 18 Telephone 203-318-9500 • Fax 203-245-2575 info@crtec.com • www.crtec.com